

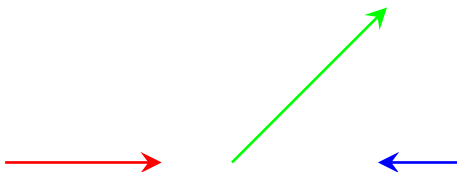
# Vector Math

CMSC 435/634

## Abstract Vectors

( $\vec{u}$ ,  $\vec{v}$ ,  $\vec{w}$  vectors;  $a$ ,  $b$ ,  $c$  scalars)

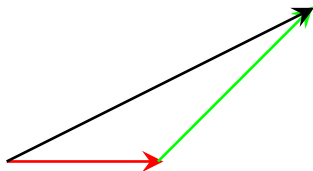
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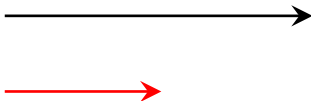
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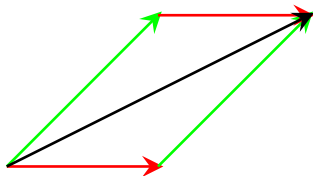
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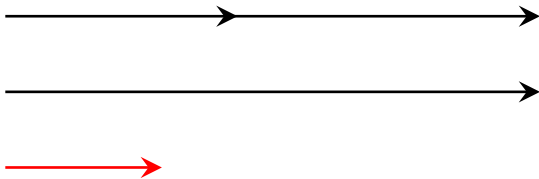
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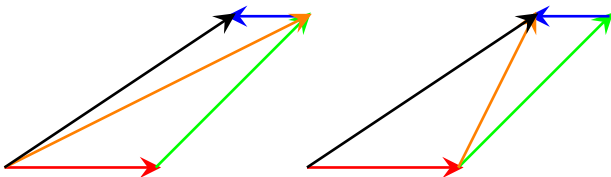
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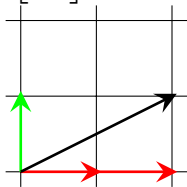
## Basis Vectors

Vector as linear combination of *basis vectors*

$$\blacktriangleright \vec{v} = 2\hat{i} + 1\hat{j} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\blacktriangleright \vec{v} = 1\hat{m} + 2\hat{n} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

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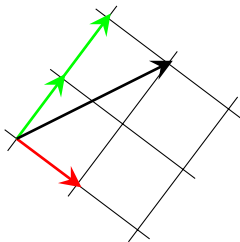
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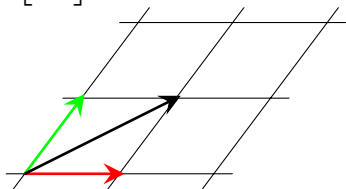
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$$\blacktriangleright \text{Column: } \vec{v} = \begin{bmatrix} v^0 \\ v^1 \end{bmatrix} \text{ (we'll usually use this form)}$$

$$\blacktriangleright \text{Row: } \vec{v} = [ v_0 \quad v_1 ] \text{ (some texts; I like for normals)}$$

## Matrices

- ▶ Matrix:  $A = \begin{bmatrix} a_0^0 & a_1^0 \\ a_0^1 & a_1^1 \end{bmatrix} = [a_j^i]$
- ▶ Transpose:  $A^T = \begin{bmatrix} a_0^0 & a_1^0 \\ a_0^1 & a_1^1 \end{bmatrix} = [a_i^j]$
- ▶ Multiply:  $AB = \begin{bmatrix} a_0^0 & a_1^0 \\ a_0^1 & a_1^1 \end{bmatrix} \begin{bmatrix} b_0^0 & b_1^0 \\ b_0^1 & b_1^1 \end{bmatrix} =$   
 $\begin{bmatrix} a_0^0 b_0^0 + a_1^0 b_0^1 & a_0^0 b_1^0 + a_1^0 b_1^1 \\ a_0^1 b_0^0 + a_1^1 b_0^1 & a_0^1 b_1^0 + a_1^1 b_1^1 \end{bmatrix} = [a_\alpha^i b_j^\alpha]$

## Adjoint and Inverse

▶ Inverse:  $A^{-1}A = AA^{-1} = I$

▶ Determinant:  $|A|$

▶  $|a| = a$

▶  $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = a|d| - b|c|$

▶  $\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$

▶ Adjoint:  $A^* = \text{cof}(A)^T$  (matrix of cofactors  $\text{cof}(A)$ )

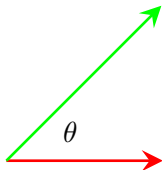
▶  $A^{-1} = \frac{A^*}{|A|}$

## Dot Product

- ▶ Also called inner product
  - ▶  $\vec{u} \bullet \vec{v}$  is a scalar
  - ▶  $\vec{u} \bullet \vec{v} = \vec{v} \bullet \vec{u}$
  - ▶  $(a\vec{u}) \bullet \vec{v} = a(\vec{u} \bullet \vec{v})$
  - ▶  $(\vec{u} + \vec{v}) \bullet \vec{w} = \vec{u} \bullet \vec{w} + \vec{v} \bullet \vec{w}$
  - ▶  $\vec{v} \bullet \vec{v} \geq 0$
  - ▶  $\vec{v} \bullet \vec{v} = 0 \leftrightarrow \vec{v} = \vec{0}$
- ▶ Matrix notation:  $\vec{u} \bullet \vec{v} = U^T V = u_\alpha v^\alpha$

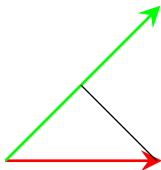
## Dot Product as Norm

- ▶  $\vec{v} \bullet \vec{v} = |\vec{v}|^2$
- ▶  $\vec{u} \bullet \vec{v} = |\vec{u}||\vec{v}| \cos \theta$ 
  - ▶ Defines angle  $\theta$ !
  - ▶ If  $|\vec{v}| = 1$ , gives projection of  $\vec{u}$  onto  $\vec{v}$
  - ▶ If  $|\vec{u}| = |\vec{v}| = 1$ , gives just  $\cos \theta$



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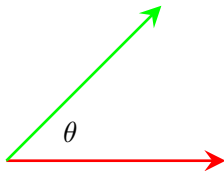
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## Orthogonal & Normal

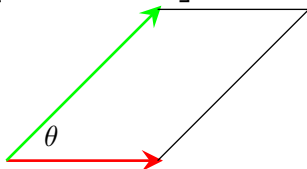
- ▶ *Orthogonal* = perpendicular:  $\vec{u} \bullet \vec{v} = 0$
- ▶ *Normal* (this usage) = unit-length:  $\vec{u} \bullet \vec{u} = 1$
- ▶ *Orthonormal*: set of vectors both orthogonal and normal
- ▶ *Orthogonal matrix*: rows (& columns) **orthonormal**
  - ▶ For orthogonal matrices,  $A^{-1} = A^T$

## 3D Cross Product

$$\vec{u} \times \vec{v}$$

- ▶ length = area of parallelogram = twice area of triangle
  - ▶  $|\vec{u} \times \vec{v}| = |\vec{u}||\vec{v}|\sin(\theta)$
- ▶ direction = perpendicular to  $\vec{u}$  and  $\vec{v}$  (right hand rule)

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} \\ \hat{j} \\ \hat{k} \end{vmatrix} \begin{vmatrix} U & V \end{vmatrix} = \begin{bmatrix} u^1 v^2 - u^2 v^1 \\ u^2 v^0 - u^0 v^2 \\ u^0 v^1 - u^1 v^0 \end{bmatrix}$$



## Building an Orthogonal Basis

Vectors  $\vec{u}$ ,  $\vec{v}$ ,  $\vec{w}$

- ▶ Gram-Schmidt (any dimension)

- ▶  $\vec{u}' = \vec{u}$

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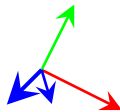
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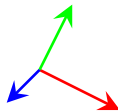
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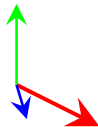
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