

GROVER'S ALGORITHM

Searching for a Needle In a Haystack

by

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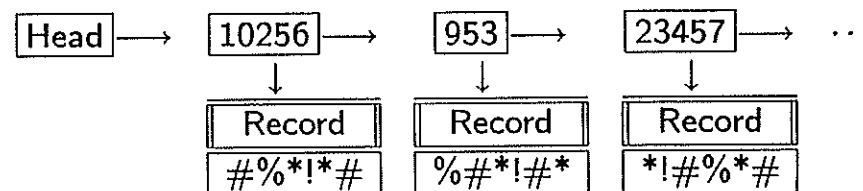
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Grover's Algorithm *Finding a Needle in a Haystack*

Consider a large unstructured database consisting of $N = 2^n$ records labelled in random order by the integers

$$0, 1, 2, \dots, N - 1$$

E.g., the database could be stored as a linked list



On average, we would have to retrieve $N/2$ labels before finding the label x_0 . Hence, the average computational work would be

$$O(N)$$

computational steps

Another Example

Consider a **plaintext/ciphertext attack by brute force key search** on a message encrypted with the *Data Encryption Standard (DES)*, where the key K is a 56 bit number.

Given the plaintext/ciphertext pair

PlainText	At0500BlowUpTheEmbassyAt
CipherText	xjejpwwziderkqldievmsfkfdlqye

crack the entire cipher by encrypting the PlainText

At0500BlowUpTheEmbassyAt

with each of the keys

$$0, 1, 2, \dots, 2^{56} - 1,$$

in turn, until the key K_0 is found that produces the CipherText

xjejpwwziderkqldievmsfkfdlqye

In other words, if

(P, C)

denotes the available plaintext/ciphertext pair, and if

K_0

denotes the key such that

$$DES(P, K_0) = C,$$

then the **oracle** is

$$f(K) = \begin{cases} 1 & \text{if } K = K_0 \\ 0 & \text{otherwise} \end{cases}$$

$I_{|\psi\rangle}$ is an Inversion

Note that

$$I_{|x_0\rangle} = I - 2|x_0\rangle\langle x_0|,$$

for

$$\begin{aligned} (I - 2|x_0\rangle\langle x_0|)|x\rangle &= |x\rangle - 2|x_0\rangle\langle x_0|x\rangle \\ &= \begin{cases} -|x_0\rangle & \text{if } x = x_0 \\ |x\rangle & \text{otherwise} \end{cases} \end{aligned}$$

Also please note for any unit length ket $|\psi\rangle$

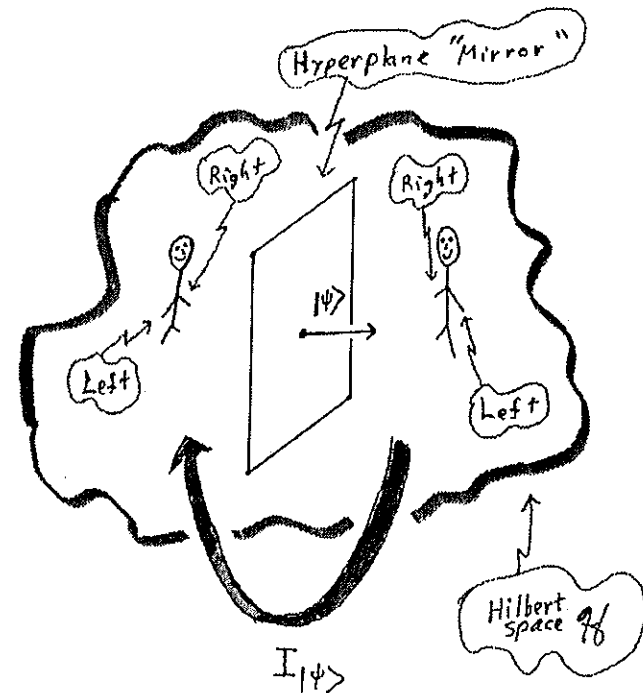
$$I_{|\psi\rangle} = I - 2|\psi\rangle\langle\psi|$$

is an **inversion** about the hyperplane \perp to $|\psi\rangle$, i.e.,

"A Mirror Image Transformation"

"A Mirror Reflection"

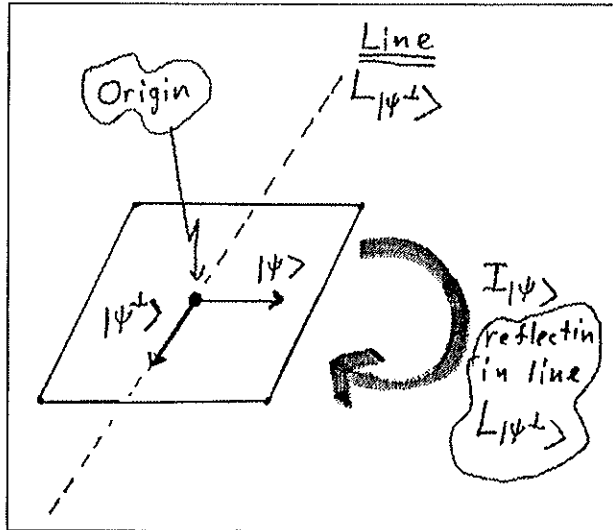
Inversion $I_{|\psi\rangle}$



Moreover, let $|\psi^\perp\rangle$ be a ket in $\mathcal{S}_{\mathbb{R}} \perp |\psi\rangle$, and let $L_{|\psi^\perp\rangle}$ denote the line in $\mathcal{S}_{\mathbb{R}}$ passing through the origin and \perp to $|\psi\rangle$. Then

$$I_{|\psi\rangle} : \mathcal{S}_{\mathbb{R}} \longrightarrow \mathcal{S}_{\mathbb{R}}$$

is a reflection in (inversion about) the line $L_{|\psi^\perp\rangle}$.



And moreover, if $|\psi^\perp\rangle$ is a unit length vector in $\mathcal{S}_{\mathbb{R}}$ which is \perp to $|\psi\rangle$, then

$$-I_{|\psi\rangle} : \mathcal{S}_{\mathbb{R}} \longrightarrow I_{|\psi^\perp\rangle} : \mathcal{S}_{\mathbb{R}}$$

And finally, if $|\psi\rangle$ is a unit length ket in \mathcal{H} , and if $U : \mathcal{H} \longrightarrow \mathcal{H}$ is a unitary transformation, then

$$UI_{|\psi\rangle}U^\dagger = I_{U|\psi\rangle}$$

What's Going On?

The Method In Lov's "Madness"

Let

$$H : \mathcal{H} \longrightarrow \mathcal{H}$$

be the Hadamard transform given by

$$H = \bigotimes_0^{n-1} H^{(2)},$$

where

$$H^{(2)} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

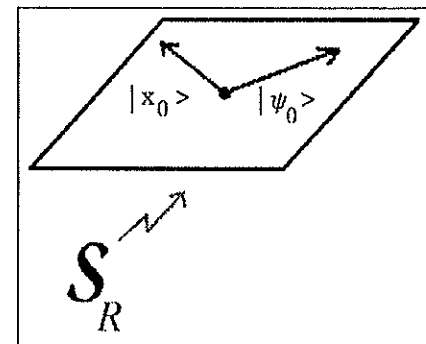
STEP 0.

This step creates a superposition of all basis states, i.e.,

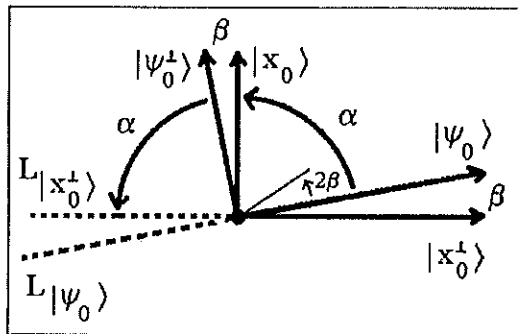
$$|0\rangle \longmapsto H|0\rangle = \frac{1}{\sqrt{N}} \sum_{j=0}^{N-1} |j\rangle = |\psi_0\rangle$$

Thus, we now have "living" in \mathcal{H} the 2-D plane

$$S_{\mathbb{R}} = \text{Span}_{\mathbb{R}}(|\psi_0\rangle, |x_0\rangle)$$



STEP 1. (Cont.)



STEP 1. (Cont.)

$$Q^k |\psi_0\rangle = \cos [(2k + 1) \beta] |x_0^\perp\rangle + \sin [(2k + 1) \beta] |x_0\rangle$$

Thus, we seek to iterate until

$$\sin [(2k + 1) \beta]$$

is as large as possible. In other words, we seek the smallest possible positive integer $k = K$ such that

$$(2k + 1) \beta$$

is as close as possible to $\pi/2$, which turns out to be

$$k = K = \text{round} \left(\frac{\pi}{4\beta} - \frac{1}{2} \right) = \left\lfloor \frac{\pi}{4\beta} \right\rfloor$$

But what is β ?

Theorem

$$\left. \begin{array}{l} L_1 \& L_2 \text{ lines in } \mathbb{R}^2 \\ L_1 \cap L_2 = \text{point } O \\ \beta = \text{Angle}(L_1, L_2) \end{array} \right\} \Rightarrow \text{Ref}_{L_2} \circ \text{Ref}_{L_1} = \text{Rot}_{2\beta} \text{ about } O$$

$$\text{Thus, } |\psi_0\rangle = \cos \beta |x_0^\perp\rangle + \sin \beta |x_0\rangle, \text{ and}$$

$$Q^k |\psi_0\rangle = \cos [(2k + 1) \beta] |x_0^\perp\rangle + \sin [(2k + 1) \beta] |x_0\rangle$$

Hence, the number of iterations in **STEP 1.** is

$$O(\sqrt{N})$$

But each iteration uses the Hadamard transform

$$H = \bigotimes_0^{n-1} H^{(2)}$$

at the computational cost of

$$O(\lg N)$$

Since **STEP 1.** is the computational dominant part of Grover's algorithm, it follows that the computational complexity of this algorithm is

$$O(\sqrt{N} \lg N)$$

The probability that the measurement performed in **STEP 2.** of Grover's algorithm will successfully retrieve the unknown label x_0 is given by

$$Prob_{Success} = \sin^2 [(2K + 1) \beta] \geq \cos^2 \beta = 1 - \frac{1}{N}$$

Grover's Algorithm

STEP 0. (Initialization)

$$|\psi\rangle \leftarrow H|0\rangle = \frac{1}{\sqrt{N}} \sum_{j=0}^{N-1} |j\rangle$$

$$k \leftarrow 0$$

STEP 1. Loop until $k = \text{round} \left(\frac{\pi}{4 \sin^{-1} \left(\frac{1}{\sqrt{N}} \right)} - \frac{1}{2} \right)$
 $\approx \text{round} \left(\frac{\pi}{4} \sqrt{N} - \frac{1}{2} \right)$

$$|\psi\rangle \leftarrow Q|\psi\rangle = -HI_{|0\rangle}HI_{|x_0\rangle}|\psi\rangle$$

$$k \leftarrow k + 1$$

STEP 2. Measure $|\psi\rangle$ with respect to the standard basis $|0\rangle, |1\rangle, \dots, |N-1\rangle$ to obtain the marked unknown state $|x_0\rangle$ with probability $\geq 1 - \frac{1}{N}$.

$$|\psi_1\rangle^T := \left[\frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \quad \frac{1}{4}\sqrt{2} \right]$$

$$|\psi_1\rangle \text{ in ket notation} := \frac{1}{8}\sqrt{2} (|000\rangle + |001\rangle + |010\rangle + |011\rangle + 5|100\rangle + |101\rangle + |110\rangle + |111\rangle)$$

> # Iteration 2: $|\psi_2\rangle := Q \cdot |\psi_1\rangle$

```
#
`psi_2`:=evalm(Q &* `psi_1`);
print(' ');
`psi_2`^T:=transpose(`psi_2`);
print(' ');
`psi_2` in ket notation:=factor(RKet(`psi_2`));
print(' ');
```

$$|\psi_2\rangle^T := \left[-\frac{1}{16}\sqrt{2} \quad -\frac{1}{16}\sqrt{2} \quad -\frac{1}{16}\sqrt{2} \quad -\frac{1}{16}\sqrt{2} \quad \frac{11}{16}\sqrt{2} \quad -\frac{1}{16}\sqrt{2} \quad -\frac{1}{16}\sqrt{2} \quad -\frac{1}{16}\sqrt{2} \right]$$

$$|\psi_2\rangle \text{ in ket notation} := -\frac{1}{16}\sqrt{2} (|000\rangle + |001\rangle + |010\rangle + |011\rangle - 11|100\rangle + |101\rangle + |110\rangle + |111\rangle)$$

> # We now exit because $K = 2$, and measure the state of our register.

On measuring the state $|\psi_2\rangle$ of our register, we obtain

```
#
Proj_4:=evalm(ket.1.0.0 &* My_Adjoint(ket.1.0.0));
Intermediate_Result:=evalm(Proj_4 &* `psi_2`);
Result:=evalm(1/norm(Intermediate_Result,2) * Intermediate_Result);
print(' ');
`Result`^T:=transpose(Result);
print(' ');
`Result` in ket notation:=RKet(Result);
print(' ');
```

$$\text{Proj}_4 := \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{Result}^T := [0 \quad 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0 \quad 0]$$

$$\text{Result in ket notation} := |100\rangle$$

> # with probability Prob_Success of success given by

```
#
Prob_Success:=(11/(8*sqrt(2)))^2;
`Prob of Success in Floating Point`:=evalf(Prob_Success);
```

$$\text{Prob. Success} = \frac{121}{128}$$

$$\text{Prob of Success in Floating Point} = 9453125000$$