





#### CMSC 461, Database Management Systems Spring 2018

# Lecture 18 – Indexing and Hashing Part 3

These slides are based on "Database System Concepts" 6<sup>th</sup> edition book (whereas some quotes and figures are used from the book) and are a modified version of the slides which accompany the book (http://codex.cs.yale.edu/avi/db-book/db6/slide-dir/index.html), in addition to the 2009/2012 CMSC 461 slides by Dr. Kalpakis

Dr. Jennifer Sleeman

https://www.csee.umbc.edu/~jsleem1/courses/461/spr18

## Logistics

- Homework #4 due 4/9/2018
- Homework #5 due 4/18/2018
- Phase 4 due 4/23/2018

#### First: B-Tree and B<sup>+</sup>-Tree Background

## **B<sup>+</sup>-Tree Index Files**

B<sup>+</sup>-tree indices are an alternative to indexed-sequential files.

- Disadvantage of indexed-sequential files
  - performance degrades as file grows, since many overflow blocks get created.
  - Periodic reorganization of entire file is required.
- Advantage of B<sup>+</sup>-tree index files:
  - automatically reorganizes itself with small, local, changes, in the face of insertions and deletions.
  - Reorganization of entire file is not required to maintain performance.
- (Minor) disadvantage of B<sup>+</sup>-trees:
  - extra insertion and deletion overhead, space overhead.
- Advantages of B<sup>+</sup>-trees outweigh disadvantages
  - B<sup>+</sup>-trees are used extensively

### **B<sup>+</sup>-Tree Index Files**

A B<sup>+</sup>-tree is a rooted tree satisfying the following properties:

- All paths from root to leaf are of the same length
- Each node that is not a root or a leaf has between [*n*/2] and *n* children.
- A leaf node has between [(n-1)/2] and n-1 values
- Special cases:
  - If the root is not a leaf, it has at least 2 children.
  - If the root is a leaf (that is, there are no other nodes in the tree), it can have between 0 and (*n*–1) values.

#### **B<sup>+</sup>-Tree Node Structure**

#### • Typical node

<i>P</i> <sub>1</sub>	<i>K</i> <sub>1</sub>	<i>P</i> <sub>2</sub>	•••	<i>P</i> <sub><i>n</i>-1</sub>	<i>K</i> <sub><i>n</i>-1</sub>	P <sub>n</sub>
-----------------------	-----------------------	-----------------------	-----	--------------------------------	--------------------------------	----------------

- K<sub>i</sub> are the search-key values
- P<sub>i</sub> are pointers to children (for non-leaf nodes) or pointers to records or buckets of records (for leaf nodes).
- The search-keys in a node are ordered

 $K_1 < K_2 < K_3 < \ldots < K_{n-1}$ 

(Initially assume no duplicate keys, address duplicates later)

### Leaf Nodes in B<sup>+</sup>-Trees

- Properties of a leaf node:
  - For i = 1, 2, ..., n-1, pointer  $P_i$  points to a file record with search-key value  $K_i$ ,
  - If L<sub>i</sub>, L<sub>j</sub> are leaf nodes and i < j, L<sub>i</sub>'s search-key values are less than or equal to L<sub>i</sub>'s search-key values
  - $P_n$  points to next leaf node in search-key order



#### **Non-Leaf Nodes in B<sup>+</sup>-Trees**

- Non leaf nodes form a multi-level sparse index on the leaf nodes. For a non-leaf node with *m* pointers:
  - All the search-keys in the subtree to which  $P_1$  points are less than  $K_1$
  - For  $2 \le i \le n 1$ , all the search-keys in the subtree to which  $P_i$  points have values greater than or equal to  $K_{i-1}$  and less than  $K_i$
  - All the search-keys in the subtree to which  $P_n$  points have values greater than or equal to  $K_{n-1}$

$$P_1 K_1 P_2 \dots P_{n-1} K_{n-1} P_n$$

## **Example of B<sup>+</sup>-tree**



• B<sup>+</sup>-tree for *instructor* file (n = 6)

- Leaf nodes must have between 3 and 5 values ([(n-1)/2] and n-1, with n = 6).
- Non-leaf nodes other than root must have between 3 and 6 children ([(n/2] and n with n =6).
- Root must have at least 2 children.

## **Queries on B<sup>+</sup>-Trees**

Find record with search-key value V. Start a C, compare V to  $K_i$ 

While C is not a leaf node do the following: if  $(V = K_i)$  Set  $C = P_{i+1}$ else Set  $C = P_i$ once  $K_i = V$ 

- If there is such a value *i*, follow pointer P<sub>i</sub> to the desired record.
   Else no record with search-key value k exists.



## **Updates on B<sup>+</sup>-Trees: Insertion**

- 1. Find the leaf node in which the search-key value would appear
- 2. If the search-key value is already present in the leaf node
  - 1. Add record to the file
  - 2. If necessary add a pointer
- 3. If the search-key value is not present, then
  - 1. Add the record to the main file
  - 2. If there is room in the leaf node, insert (key-value, pointer) pair in the leaf node
  - 3. Otherwise, split the node (along with the new (key-value, pointer) entry) as discussed in the next slide.

# **Updates on B<sup>+</sup>-Trees: Insertion**

<u>Leaf Full</u>	<u>Index Full</u>	<u>Action</u>
No	No	Place the record in sorted position in the appropriate leaf node
Yes	No	<ol> <li>Split the leaf</li> <li>Place middle key in the index node in sorted order</li> <li>Left leaf node contains records with keys below the middle key.</li> <li>Right leaf node contains records with keys equal to or greater than the middle key.</li> </ol>
Yes	Yes	<ol> <li>Split the leaf node.</li> <li>Records with keys &lt; middle key go to the left leaf node.</li> <li>Records with keys &gt;= middle key go to the right leaf node.</li> <li>Split the index node.</li> <li>Keys &lt; middle key go to the left index node.</li> <li>Keys &gt; middle key go to the right index node.</li> <li>Keys &gt; middle key goes to the next (higher level) index.</li> <li>IF the next level index node is full, continue splitting the index node.</li> </ol>

## **Updates on B<sup>+</sup>-Trees: Insertion**

- Splitting a leaf node:
  - take the *n* (search-key value, pointer) pairs (including the one being inserted) in sorted order. Place the first [*n*/2] in the original node, and the rest in a new node.
  - let the new node be p, and let k be the least key value in p. Insert
     (k,p) in the parent of the node being split.
  - If the parent is full, split it and **propagate** the split further up.
- Splitting of nodes proceeds upwards till a node that is not full is found.



- Result of splitting node containing Brandt, Califieri and Crick on inserting Adams
- . Next step: insert entry with (Califieri, pointer-to-new-node) into parent

### **B<sup>+</sup>-Trees Insertion**





• B<sup>+</sup>-Tree before and after insertion of "Adams"

#### **B<sup>+</sup>-Trees Insertion**



• B<sup>+</sup>-Tree before and after insertion of "Lamport"

# **Updates on B<sup>+</sup>-Trees: Deletion**

<u>Leaf Node Below</u> <u>Fill Factor</u>	<u>Index Node Below</u> <u>Fill Factor</u>	<u>Action</u>
No	No	<ol> <li>Delete the record from the leaf node</li> <li>Arrange keys in ascending order to fill void</li> <li>If the key of the deleted record appears in the index node, use the next key to replace it.</li> </ol>
Yes	No	<ol> <li>Combine the leaf node and its sibling</li> <li>Change the index node to reflect the change</li> </ol>
Yes	Yes	<ol> <li>Combine the leaf node and its sibling</li> <li>Adjust the index node to reflect the change</li> <li>Combine the index node with its sibling</li> <li>Continue combining index node until you reach a node with the correct fill factor or you reach the root node</li> </ol>

### **Example of B<sup>+</sup>-tree Deletion**



Before and after deleting "Srinivasan"



Deleting "Srinivasan" causes merging of under-full leaves

### **Example of B<sup>+</sup>-tree Deletion**



- · Deletion of "Singh" and "Wu" from result of previous example
- Leaf containing Singh and Wu became underfull, and borrowed a value Kim from its left sibling
- Search-key value in the parent changes as a result

# Hashing

- A bucket is a unit of storage containing one or more records (a bucket is typically a disk block).
- In a hash file organization we obtain the bucket of a record directly from its search-key value using a hash function.

 Hash function *h* is a function from the set of all search-key values *K* to the set of all bucket addresses *B*.

*h*(*K*<sub>*i*</sub>)=address of the bucket where record is stored



- Hash function is used to locate records for <u>access</u>, <u>insertion</u> as well as <u>deletion</u>.
- Records with different search-key values may be mapped to the same bucket
- Entire bucket has to be searched sequentially to locate a record



#### **Hash Functions**

 Worst hash function maps all search-key values to the same bucket; this makes access time proportional to the number of search-key values in the file.

### **Hash Functions**

- An ideal hash function is uniform, i.e., each bucket is assigned the same number of search-key values from the set of *all* possible values
- Ideal hash function is random, so each bucket will have the same number of records assigned to it irrespective of the actual distribution of search-key values in the file

#### AND...should be easy/fast to compute

#### **Hash Functions**

 Typical hash functions perform computation on the internal binary representation of the search-key.

## **Example of Hash File Organization**

#### bucket 0

#### bucket 1

15151	Mozart	Music	40000

#### bucket 2

32343	El Said	History	80000
58583	Califieri	History	60000

#### bucket 3

22222	Einstein	Physics	95000
33456	Gold	Physics	87000
98345	Kim	Elec. Eng.	80000

#### bucket 4

12121	Wu	Finance	90000
76543	Singh	Finance	80000

bucket 5

76766	Crick	Biology	72000

bucket 6

10101	Srinivasan	Comp. Sci.	65000
45565	Katz	Comp. Sci.	75000
83821	Brandt	Comp. Sci.	92000

bucket 7



Hash file organization of *instructor* file, using *dept\_name* as key

# **Example of Hash File Organization**

. There are 8 buckets,

- The binary representation of the *i*th character is assumed to be the integer
- The hash function returns the sum of the binary representations of the characters modulo 8

	. 0		
bucket	:1		
15151	Mozart	Music	40000

oucket 2						
32343 El Said History 8000						
58583	Califieri	History	60000			

bucket 3				
22222	Einstein	Physics	95000	
33456	Gold	Physics	87000	
98345	Kim	Elec. Eng.	80000	

bucket	4		
12121	Wu	Finance	90000
76543	Singh	Finance	80000

bucket 5

76766	Crick	Biology	72000

bucket 6

	10101	Srinivasan	Comp. Sci.	65000
	45565	Katz	Comp. Sci.	75000
	83821	Brandt	Comp. Sci.	92000

bucket 7

$$\begin{array}{ll}h(\text{Music}) = 1 & h(\text{History}) = 2\\h(\text{Physics}) = 3 & h(\text{Elec. Eng.}) = 3\end{array}$$

## Handling of Bucket Overflows

- Bucket overflow can occur because of
  - Insufficient buckets
  - Skew in distribution of records. This can occur due to two reasons:
    - multiple records have same search-key value
    - chosen hash function produces non-uniform distribution of key values
- Although the probability of bucket overflow can be reduced, it cannot be eliminated; it is handled by using overflow buckets.

### Handling of Bucket Overflows

- Overflow chaining the overflow buckets of a given bucket are chained together in a linked list.
- Above scheme is called **closed hashing**.
  - An alternative, called **open hashing**, which does not use overflow buckets, is not suitable for database applications.



### Hash Indices

- Hashing can also for index-structure creation.
- A hash index organizes the search keys, with their associated record pointers, into a hash file structure.
- Strictly speaking, hash indices are always secondary indices
  - if the file itself is organized using hashing, a separate primary hash index on it using the same search-key is unnecessary.

- However, we use the term hash index to refer to both secondary index structures and hash organized files.

#### **Example of Hash Index**



What do you think?

 In static hashing, function h maps search-key values to a fixed set of B of bucket addresses. Databases grow or shrink with time.





- One solution: periodic re-organization of the file with a new hash function
  - Expensive, disrupts normal operations
- Better solution: allow the number of buckets to be modified dynamically

#### **Dynamic Hashing**

# **Dynamic Hashing**

- Good for database that grows and shrinks in size
- Allows the hash function to be modified dynamically
- Extendable hashing one form of dynamic hashing

### **Extendable Hashing**

- Hash function generates values over a large range typically *b*-bit integers, with b = 32.
- At any time use only a <u>prefix</u> of the hash function to index into a table of bucket addresses

#### **Extendable Hashing**

Let the length of the prefix be *i* bits,  $0 \le i \le 32$ 

Bucket address table size =  $2^{i}$ .

```
Initially i = 0
```

Value of *i* grows and shrinks as the size of the database grows and shrinks.

### **Extendable Hashing**

- Multiple entries in the bucket address table may point to a bucket
- Actual number of buckets is  $< 2^i$
- The number of buckets changes dynamically due to coalescing and splitting of buckets



#### **General Extendable Hash Structure**



In this structure,  $i_2 = i_3 = i$ , whereas  $i_1 = i - 1$ 

#### Use of Extendable Hash Structure

- Each bucket *j* stores a value *i<sub>j</sub>* All the entries that point to the same bucket have the same values on the first  $i_j$  bits.
- To locate the bucket containing search-key

  - *K*: 1. Compute  $h(K_i) = X$ 2. Use the first *i* high order bits of *X* as a displacement into bucket address table, and follow the pointer to appropriate bucket

#### **Insertion in Extendable Hash Structure**

To insert a record with search-key value *K*<sub>j</sub> Follow same procedure as look-up and locate the bucket, say *j*.

If there is room in the bucket *j* insert record in the bucket.

Else the bucket must be split and insertion re-attempted

#### **Insertion in Extendable Hash Structure**

If  $i > i_j$  (more than one pointer to bucket j) Allocate a new bucket z, and set  $i_j = i_z = (i_j + 1)$ Update the second half of the bucket address table entries originally pointing to j, to point to zRemove each record in bucket j and reinsert (in j or z) Recompute new bucket for  $K_j$  and insert record in the bucket (further splitting is required if the bucket is still full)

#### Insertion in Extendable Hash Structure

- If i = i, (only one pointer to bucket j)
   If i reaches some limit b, or too many splits have
   happened in this insertion, create an overflow bucket
   Else
  - □ Increment *i* and double the size of the bucket address table.
  - Replace each entry in the table by two entries that point to the same bucket.
  - □ Recompute new bucket address table entry for  $K_j$ Now  $i > i_j$  so use the first case above.

#### **Deletion in Extendable Hash Structure**

To delete a key value,

Locate it in its bucket and remove it.

The bucket itself can be removed if it becomes empty (with appropriate updates to the bucket address table).

Coalescing of buckets can be done (can coalesce only with a "*buddy*" bucket having same value of  $i_j$ and same  $i_j -1$  prefix, if it is present) Decreasing bucket address table size is also possible

Note: decreasing bucket address table size is an expensive operation and should be done only if number of buckets becomes much smaller than the size of the table

#### **Use of Extendable Hash Structure: Example**

dept\_name

Biology Comp. Sci. Elec. Eng. Finance History Music Physics h(*dept\_name*)

0010 1101 1111 1011 0010 1100 0011 0000 1111 0001 0010 0100 1001 0011 0110 1101 0100 0011 1010 1100 1100 0110 1101 1111 1010 0011 1010 0000 1100 0110 1001 1111 1100 0111 1110 1101 1011 1111 0011 1010 0011 0101 1010 0110 1100 1001 1110 1011 1001 1000 0011 1111 1001 1100 0000 0001

Initial Hash structure; bucket size = 2



dept\_name

1

#### h(*dept\_name*)

Biology	0010 1101 1111 1011 0010 1100 0011 0000
Comp. Sci.	1111 0001 0010 0100 1001 0011 0110 1101
Elec. Eng.	0100 0011 1010 1100 1100 0110 1101 1111
Finance	1010 0011 1010 0000 1100 0110 1001 1111
History	1100 0111 1110 1101 1011 1111 0011 1010
Music	0011 0101 1010 0110 1100 1001 1110 1011
Physics	1001 1000 0011 1111 1001 1100 0000 0001

Hash structure after insertion of "Mozart", "Srinivasan", and "Wu" records



Hash structure after insertion of Einstein record





Hash structure after insertion of Katz record



h(*dept\_name*) dept\_name Biology 0010 1101 1111 1011 0010 1100 0011 0000 Comp. Sci. 1111 0001 0010 0100 1001 0011 0110 1101 Elec. Eng. 0100 0011 1010 1100 1100 0110 1101 1111 Finance 1010 0011 1010 0000 1100 0110 1001 1111 History 1100 0111 1110 1101 1011 1111 0011 1010 Music 0011 0101 1010 0110 1100 1001 1110 1011 Physics 1001 1000 0011 1111 1001 1100 0000 0001





#### **Extendable Hashing vs. Other Schemes**

- Benefits of extendable hashing:
  - Hash performance does not degrade with growth of file
  - Minimal space overhead
- Disadvantages of extendable hashing
  - Extra level of indirection to find desired record
  - Bucket address table may itself become very big (larger than memory)
    - Cannot allocate very large contiguous areas on disk either
    - Solution: B<sup>+</sup>-tree structure to locate desired record in bucket address table
  - Changing size of bucket address table is an expensive operation
- Linear hashing is an alternative mechanism
  - Allows incremental growth of its directory (equivalent to bucket address table)
  - At the cost of more bucket overflows

#### **Comparison of Ordered Indexing and Hashing**

- Cost of periodic re-organization
- Relative frequency of insertions and deletions
- Is it desirable to optimize average access time at the expense of worst-case access time?
- Expected type of queries

#### **Comparison of Ordered Indexing and Hashing**

Expected type of queries:

- Hashing is generally better at retrieving records having a specified value of the key.
- If range queries are common, ordered indices are to be preferred

In practice:

- PostgreSQL supports hash indices, but discourages use due to poor performance
- MySQL supports hash indices
- Oracle supports static hash organization, but not hash indices
- SQLServer supports only B<sup>+</sup>-trees

#### **Bitmap Indices**

## **Bitmap Indices**

- Bitmap indices are a special type of index designed for efficient querying on multiple keys
- Records in a relation are assumed to be numbered sequentially from, say, 0
  - Given a number n it must be easy to retrieve record n
    - Particularly easy if records are of fixed size
- Applicable on attributes that take on a relatively small number of distinct values
  - E.g. gender, country, state, ...
  - E.g. income-level (income broken up into a small number of levels such as 0-9999, 10000-19999, 20000-50000, 50000- infinity)
- A bitmap is simply an array of bits

# **Bitmap Indices (Cont.)**

- In its simplest form a bitmap index on an attribute has a bitmap for each value of the attribute
  - Bitmap has as many bits as records
  - In a bitmap for value v, the bit for a record is 1 if the record has the value v for the attribute, and is 0 otherwise



# **Bitmap Indices (Cont.)**

- Bitmap indices are useful for queries on multiple attributes
  - not particularly useful for single attribute queries
- Queries are answered using bitmap operations
  - Intersection (and)
  - Union (or)
  - Complementation (not)

# **Bitmap Indices (Cont.)**

- Each operation takes two bitmaps of the same size and applies the operation on corresponding bits to get the result bitmap

   E.g. 100110 AND 110011 = 100010
   100110 OR 110011 = 110111
   NOT 100110 = 011001
  - Males with income level L1: 10010 AND 10100
    - = 10000
    - Can then retrieve required tuples.
    - Counting number of matching tuples is even faster

#### **Index Definition in SQL**

 Create an index create index <index-name> on <relation-name> (<attribute-list>)
 E.g.: create index b-index on branch(branch\_name)

### Index Definition in SQL

- Use create unique index to indirectly specify and enforce the condition that the search key is a candidate key is a candidate key.
  - Not really required if SQL unique integrity constraint is supported
- To drop an index

drop index <index-name>

 Most database systems allow specification of type of index, and clustering.