

Lecture 1: 2024-02-19 Features 2

*Lecturer: Tejas Gokhale**Scribe: Matthew Hambrecht*

Disclaimer: *These notes have not been subjected to the usual scrutiny reserved for formal publications. They may be distributed outside this class only with the permission of the Instructor.*

1.1 Scale Invariant Feature Transform

Algorithm 1: SIFT

1. Take 16x16 window around detected feature
 2. Divide window into 4x4 grid of cells
 3. Compute an orientation histogram for each cell.
 4. 16 cells * 8 orientations = 128 descriptors
-

1.1.1 Feature Distance

L2 Distance:

$$\|f_1 - f_2\| \quad (1.1)$$

Ratio distance:

$$\|f_1 - f_2\| \div \|f_1 - f'_2\| \quad (1.2)$$

1.1.1.1 Evaluating the results

- Utilize ROC curve ("Receiver Operator Characteristic") to evaluate results.

1.2 Machine Learning for Computer Vision

Motivations

- Image Classification

Challenges with feature detection:

- Viewpoint variation
- Illumination
- Background clutter

- Occlusion
- Pose and Deformation
- Inter-Class Variation
- Illusions

Answer to challenges: **Data Supervised Learning:** Learning from examples (training data).

Questions on how to implement Machine Learning in Computer Vision:

- How to represent images for classifications?
 - Matrix
- How to represent class labels?
 - Integers (*i.e.* $1 = \text{Fish}$, $2 = \text{Grizzly}$)
 - Strings (*i.e.* "Fish", "Grizzly", *etc.*)
 - One hot vectors (*i.e.* $[0, 0, 1] = \text{Fish}$, $[0, 1, 0] = \text{Grizzly}$)
- What should loss be?
 - 0-1 loss (Number of misclassifications)
 - Cross entropy (Approximation of 0-1 loss)
- What is the output?
 - Probability from 0 - 1 of predicted classes

Generalization: The central challenge in machine learning is that our algorithm must perform well on new, previously unseen inputs—not just those on which our model was trained.