



# Search in Python

Chapter 3

# Today's topics

- AIMA Python code
- What it does
- How to use it
- Worked example: water jug program



# Install AIMA Python ?

- [Aimacode](#) is a great github repo of python code linked to the AIMA book
- It's not available for pip installing 😞
  - Peter Norvig's recommendation
- One workaround is to:
  - Clone repo on your computer and follow instructions in its [readme file](#)
  - Add directory to your [PYTHONPATH](#) environment variable
  - Use it with [Binder](#)

# Two Water Jugs Problem



- Given two water jugs,  $J1$  and  $J2$ , with capacities  $C1$  and  $C2$  and initial amounts  $W1$  and  $W2$ , find actions to end up with amounts  $W1'$  and  $W2'$  in the jugs
- Example problem:
  - We have a 5 gallon and 2 gallon jug
  - Initially both are full
  - We want to end up with exactly one gallon in  $J2$  and don't care how much is in  $J1$

# search.py

- Defines a *Problem* class for a search problem
- Has functions to do various kinds of search given an instance of a *Problem*, e.g., BFS, DFS, & more
- *InstrumentedProblem* subclasses *Problem* and is used with *compare\_searchers* for evaluation
- To use for WJP:
  1. Decide how to represent it (i.e., state, actions, goal);
  2. Define *WJP* as a subclass of *Problem*; and
  3. Provide methods to (a) create a WJP instance, (b) compute state successors, and (c) test for a goal

# Example: Water Jug Problem



Given full 5-gal. jug  
and empty 2-gal. jug,  
fill 2-gal jug with one  
gallon

- State =  $(x,y)$ , where  $x$  is water in jug 1;  $y$  is water in jug 2
- Initial State =  $(5,0)$
- Goal State =  $(-1,1)$ , where -1 means any amount

Action table

Name	Cond.	Transition	Effect
dump1	$x > 0$	$(x,y) \rightarrow (0,y)$	Empty Jug 1
dump2	$y > 0$	$(x,y) \rightarrow (x,0)$	Empty Jug 2
pour_1_2	$x > 0$ & $y < C2$	$(x,y) \rightarrow (x-D, y+D)$ $D = \min(x, C2-y)$	Pour from Jug 1 to Jug 2
pour_2_1	$y > 0$ & $X < C1$	$(x,y) \rightarrow (x+D, y-D)$ $D = \min(y, C1-x)$	Pour from Jug 2 to Jug 1

# Our WJ problem class



```
class WJ(Problem):  
    def __init__(self, capacities=(5,2), initial=(5,0), goal=(0,1)):  
        self.capacities = capacities  
        self.initial = initial  
        self.goal = goal  
  
    def goal_test(self, state): # returns True iff state is a goal state  
        g = self.goal  
        return (state[0] == g[0] or g[0] == -1 ) and  
                (state[1] == g[1] or g[1] == -1)  
  
    def __repr__(self): # returns string representing the object  
        return f"WJ({self.capacities},{self.initial},{self.goal}"
```

Note: f-string

# Returns list of possible actions in state

```
def actions(self, state):
```

```
    (J1, J2) = state
```

```
    (C1, C2) = self.capacities
```

```
    acts = []
```

```
    if J1>0: acts.append(('dump', 1))
```

```
    if J2>0: acts.append(('dump', 2))
```

```
    if J2<C2 and J1>0: acts.append(('pour', 1, 2))
```

```
    if J1<C1 and J2>0: acts.append(('pour', 2, 1))
```

```
    return acts
```

*Note: we represent an action as a tuple of its name and arguments, e.g.*

- *(dump, 1)*
- *(pour 2, 1)*



```
def result(self, state, action):
    """ Given state and action, returns successor
        after doing action """
    if len(action) == 2:
        act, arg1 = action
    else:
        act, arg1, arg2 = action
    (J1, J2), (C1, C2) = state, self.capacities
    if act == 'dump':
        return (0, J2) if arg1 == 1 else (J1, 0)
    elif act == 'pour':
        if arg1 == 1:
            delta = min(J1, C2-J2)
            return (J1-delta, J2+delta)
        else:
            delta = min(J2, C1-J1)
            return (J1+delta, J2-delta)
```

# Result returns successor state

*Note: the AIMA  
code will call this  
for each possible  
action that can be  
done in a state*

# Our WJ problem class

```
def h(self, node):  
    # heuristic function that estimates distance  
    # to a goal node  
    return 0 if self.goal_test(node.state) else 1
```

*Note: this is only  
useful for informed  
search algorithms*

# Solving a WJP

```
code> python
```

```
>>> from wj import *
```

```
# Import wj.py and search.py
```

```
>>> from search import *
```

```
>>> p1 = WJ((5,2), (5,2), ('*', 1))
```

```
# Create a problem instance
```

```
>>> p1
```

```
WJ((5, 2),(5, 2),('*', 1))
```

```
>>> answer = breadth_first_search(p1)
```

```
# Used the breadth 1st search function
```

```
>>> answer
```

```
# Will be None if the search failed or a
```

```
<Node (0, 1)>
```

```
# a goal node in the search graph if successful
```

```
>>> answer.path_cost
```

```
# The cost to get to every node in the search graph
```

```
6
```

```
# is maintained by the search procedure
```

```
>>> path = answer.path()
```

```
# A node's path is the best way to get to it from
```

```
>>> path
```

```
# the start node, i.e., a solution
```

```
[<Node (5, 2)>, <Node (5, 0)>, <Node (3, 2)>, <Node (3, 0)>, <Node (1, 2)>, <Node (1, 0)>, <Node (0, 1)>]
```

# Comparing Search Algorithms Results

**Uninformed searches:** breadth\_first\_tree\_search, breadth\_first\_search, depth\_first\_graph\_search, iterative\_deepening\_search, depth\_limited\_search

- All but depth\_limited\_search are **sound** (i.e., solutions found are correct)
- Not all are **complete** (i.e., can find all solutions)
- Not all are **optimal** (find best possible solution)
- Not all are **efficient**
- AIMA code has a comparison function

# Comparing Search Algorithms Results

```
HW2> python
```

```
Python 2.7.6 |Anaconda 1.8.0 (x86_64)| ...
```

```
>>> from wj import *
```

```
>>> searchers=[breadth_first_search, depth_first_graph_search,  
iterative_deepening_search]
```

```
>>> compare_searchers([WJ((5,2), (5,0), (0,1))], ['SEARCH ALGORITHM',  
'successors/goal tests/states generated/solution'], searchers)
```

```
SEARCH ALGORITHM      successors/goal tests/states generated/solution
```

```
breadth_first_search   < 8/ 9/ 16/(0, >
```

```
depth_first_graph_search < 5/ 6/ 12/(0, >
```

```
iterative_deepening_search < 35/ 61/ 57/(0, >
```

```
>>>
```

# The Output

```
hhw2> python wjtest.py -s 5 0 -g 0 1
```

```
Solving WJ((5, 2),(5, 0),(0, 1)
```

```
breadth_first_tree_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
breadth_first_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
depth_first_graph_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
iterative_deepening_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
astar_search cost 5: (5, 0) (3, 2) (3, 0) (1, 2) (1, 0) (0, 1)
```

```
SUMMARY: successors/goal tests/states generated/solution
```

```
breadth_first_tree_search < 25/ 26/ 37/(0, >
```

```
breadth_first_search < 8/ 9/ 16/(0, >
```

```
depth_first_graph_search < 5/ 6/ 12/(0, >
```

```
iterative_deepening_search < 35/ 61/ 57/(0, >
```

```
astar_search < 8/ 10/ 16/(0, >
```